

FIG. 1 is a schematic diagram of a system 100 for controlling a vehicle 110. The system 100 includes a controller 105, a sensor 115, an actuator 120, and a display 125. The controller 105 is connected to the sensor 115, the actuator 120, and the display 125. The sensor 115 is connected to the controller 105 via a line 130. The actuator 120 is connected to the controller 105 via a line 140. The display 125 is connected to the controller 105 via a line 150. The controller 105 is also connected to a power source 160 via a line 170. The power source 160 is connected to the controller 105 via a line 175. The system 100 is configured to control the vehicle 110 based on data received from the sensor 115 and data received from the power source 160. The controller 105 can output control signals to the actuator 120 and the display 125. The display 125 can display information to a user of the vehicle 110. The actuator 120 can perform actions on the vehicle 110 based on control signals received from the controller 105. The power source 160 can provide power to the controller 105. The sensor 115 can sense data about the vehicle 110 and output the data to the controller 105. The controller 105 can process the data and output control signals to the actuator 120 and the display 125. The system 100 can be used to control a variety of vehicles, including cars, trucks, and boats. The system 100 can be used to control a variety of vehicle functions, including steering, acceleration, and braking. The system 100 can be used to control a variety of vehicle systems, including the engine, the transmission, and the brakes. The system 100 can be used to control a variety of vehicle components, including the wheels, the suspension, and the steering system. The system 100 can be used to control a variety of vehicle parameters, including the speed, the direction, and the position. The system 100 can be used to control a variety of vehicle behaviors, including the acceleration, the deceleration, and the turning. The system 100 can be used to control a variety of vehicle states, including the starting, the stopping, and the idling. The system 100 can be used to control a variety of vehicle modes, including the driving, the parking, and the towing. The system 100 can be used to control a variety of vehicle functions, including the engine, the transmission, and the brakes. The system 100 can be used to control a variety of vehicle components, including the wheels, the suspension, and the steering system. The system 100 can be used to control a variety of vehicle parameters, including the speed, the direction, and the position. The system 100 can be used to control a variety of vehicle behaviors, including the acceleration, the deceleration, and the turning. The system 100 can be used to control a variety of vehicle states, including the starting, the stopping, and the idling. The system 100 can be used to control a variety of vehicle modes, including the driving, the parking, and the towing.

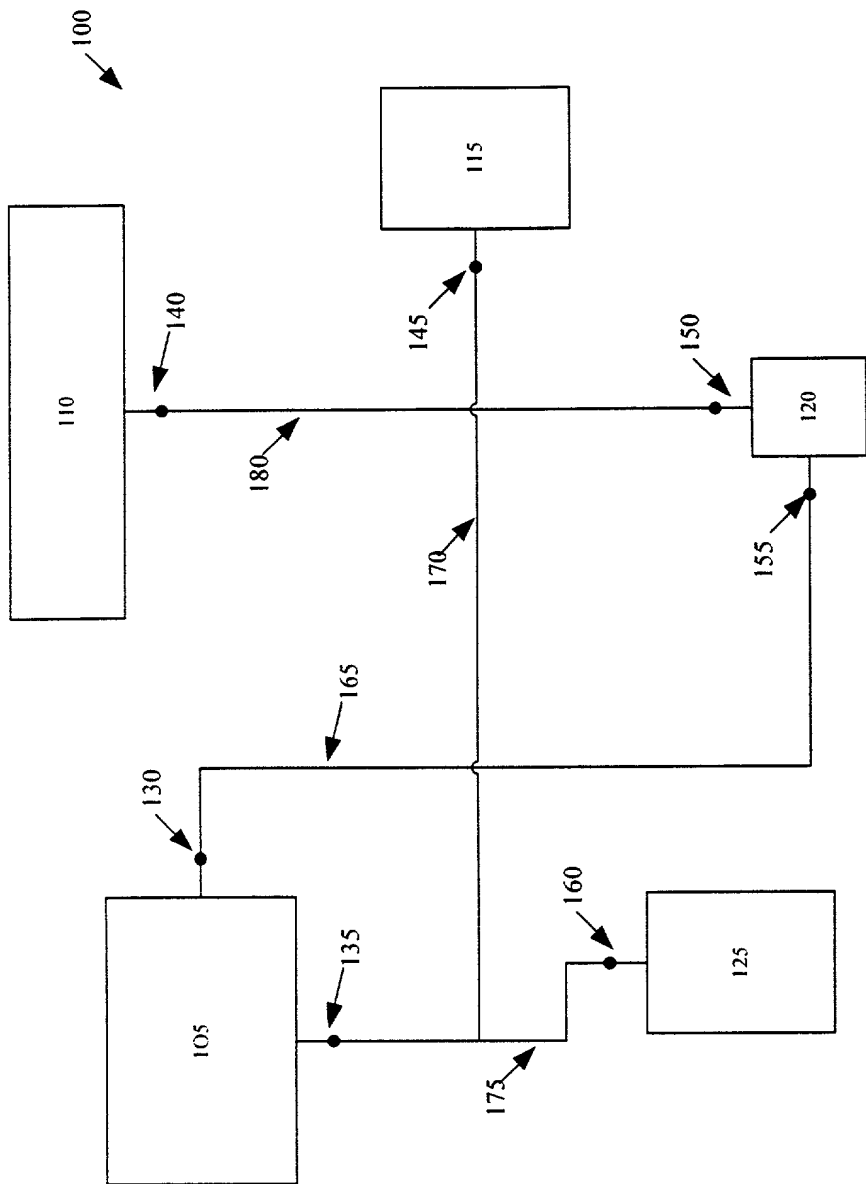


Figure 1

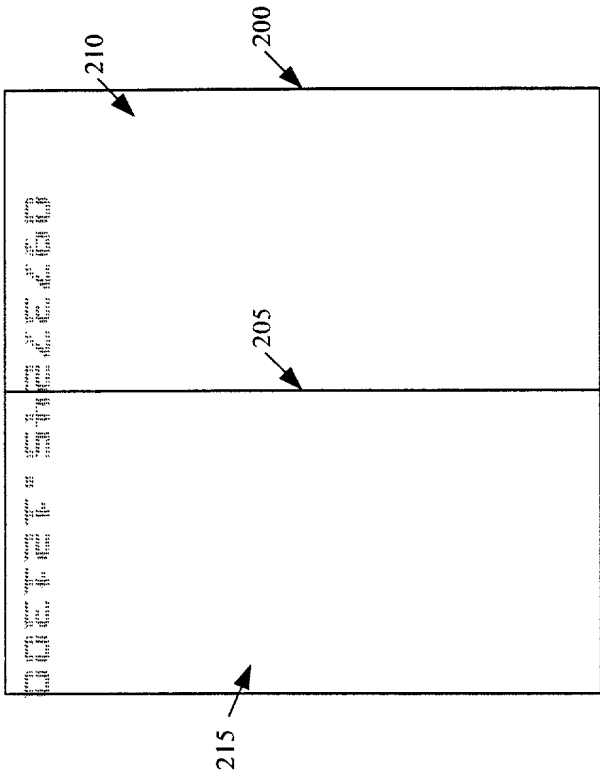


Figure 2

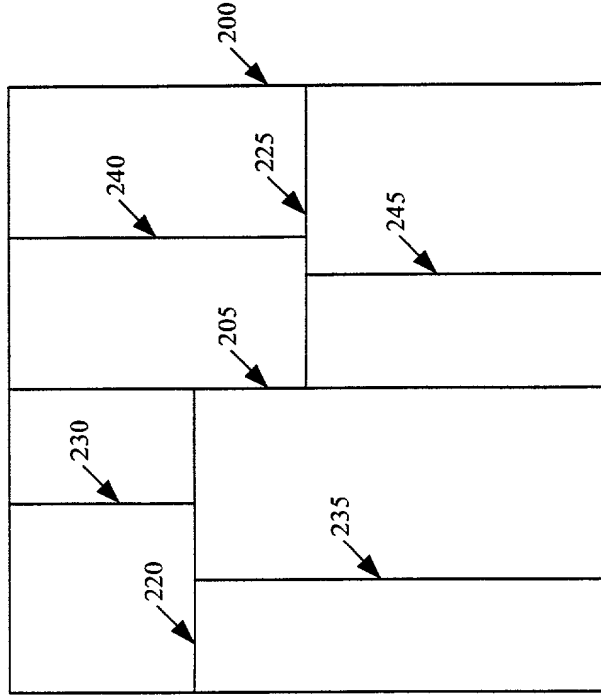


Figure 3

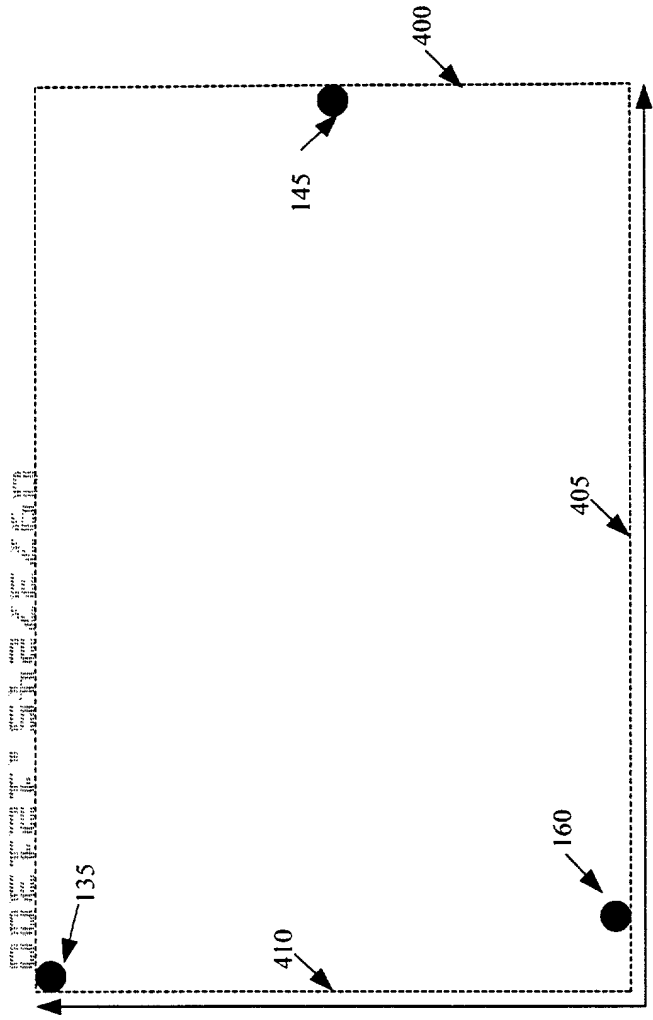


Figure 4

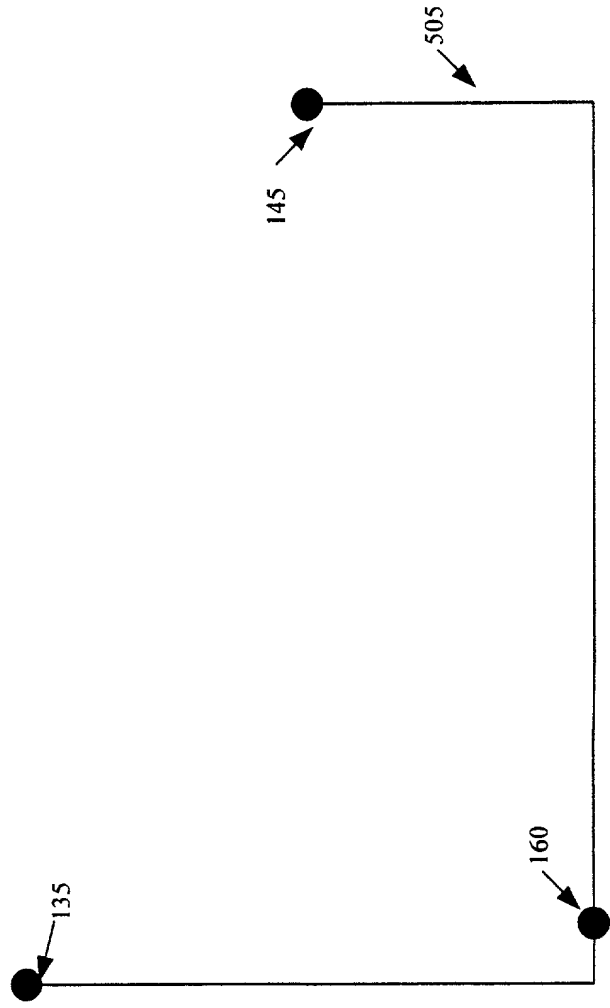


Figure 5

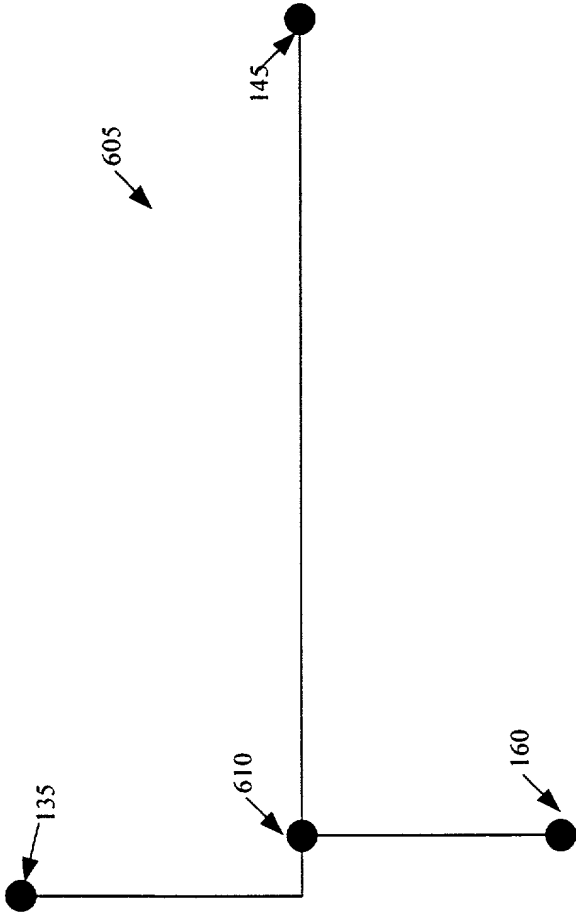


Figure 6

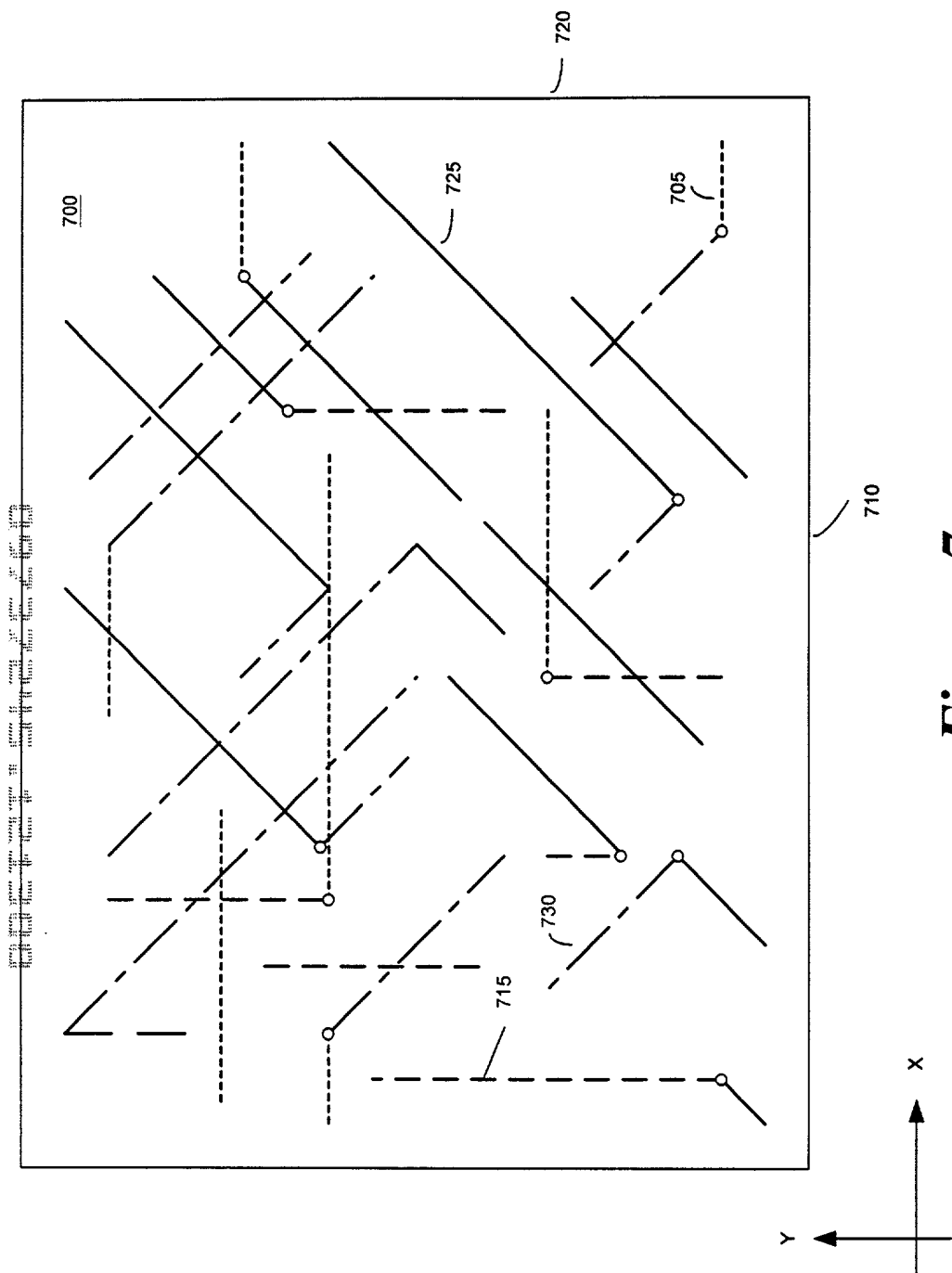


Figure 7

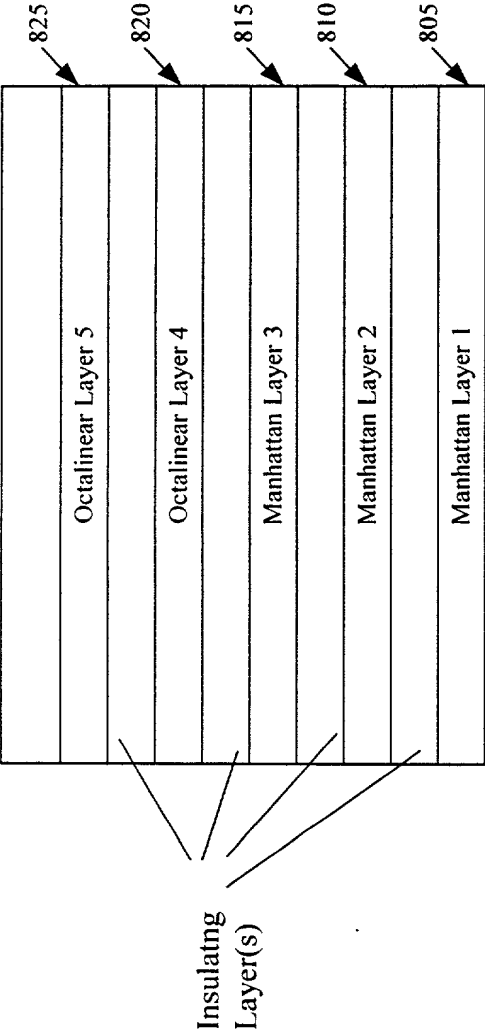


Figure 8

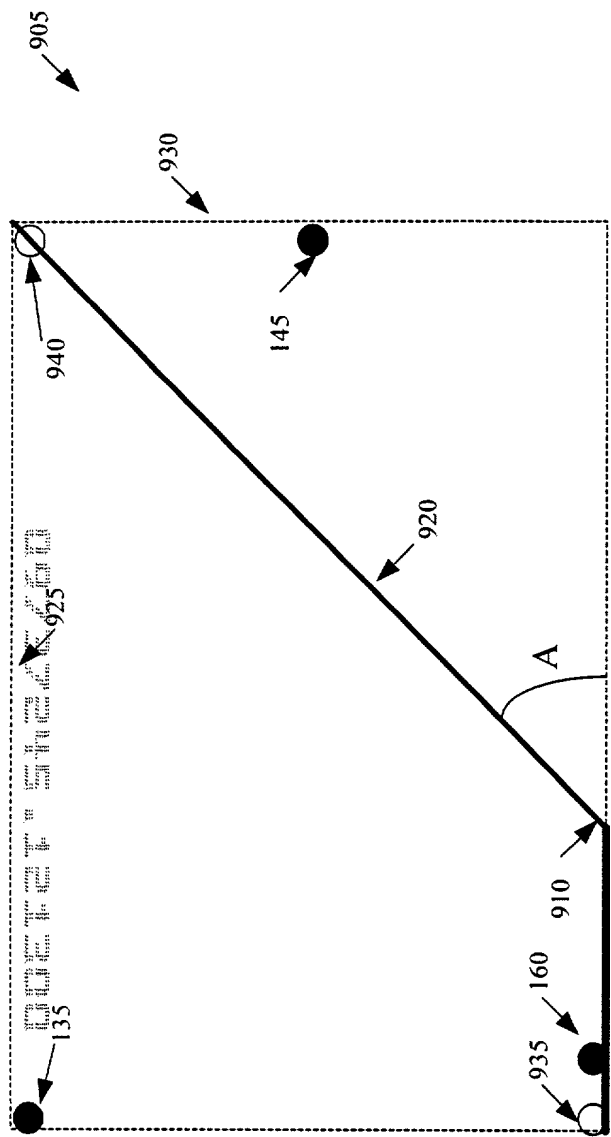


Figure 9

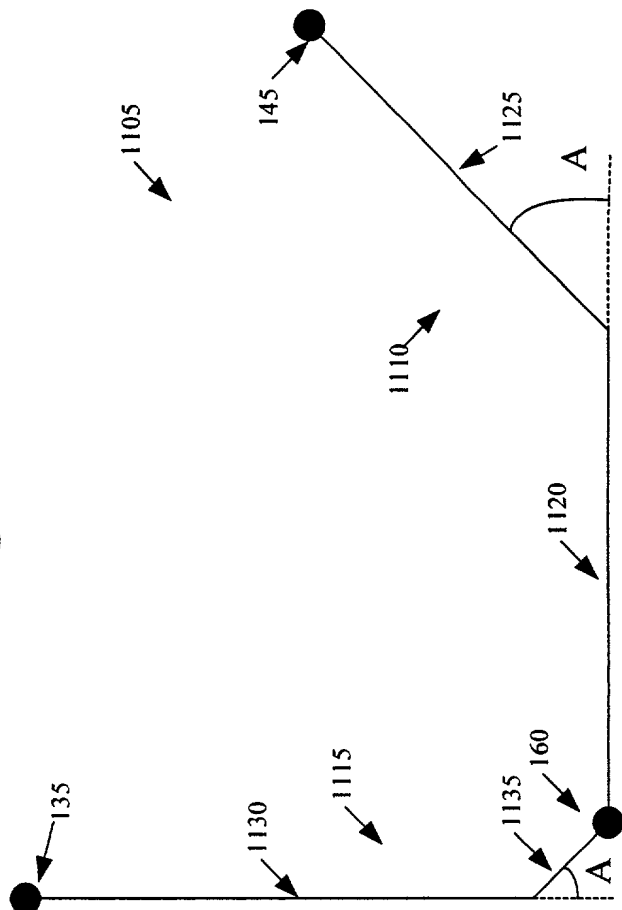


Figure 11

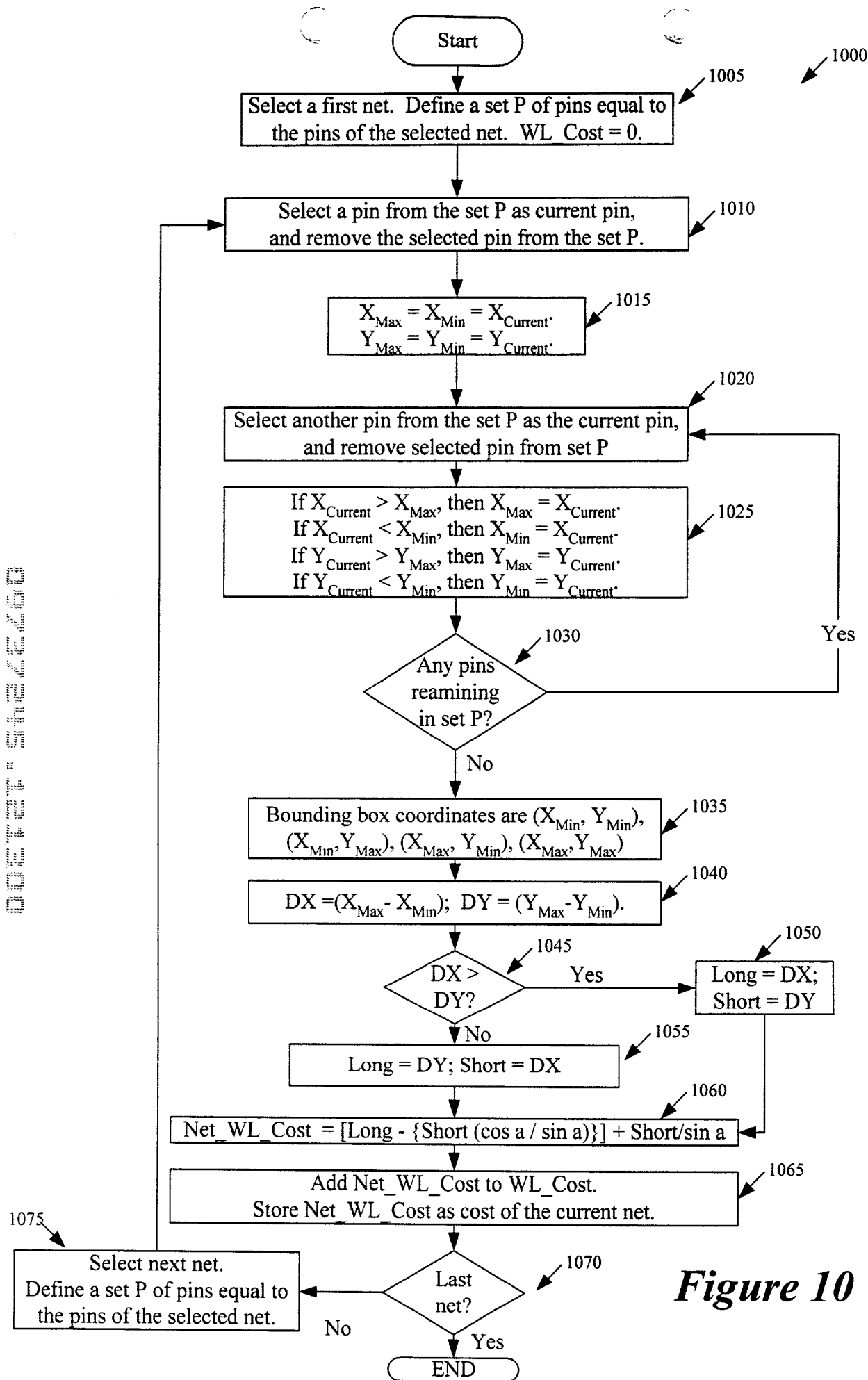


Figure 10

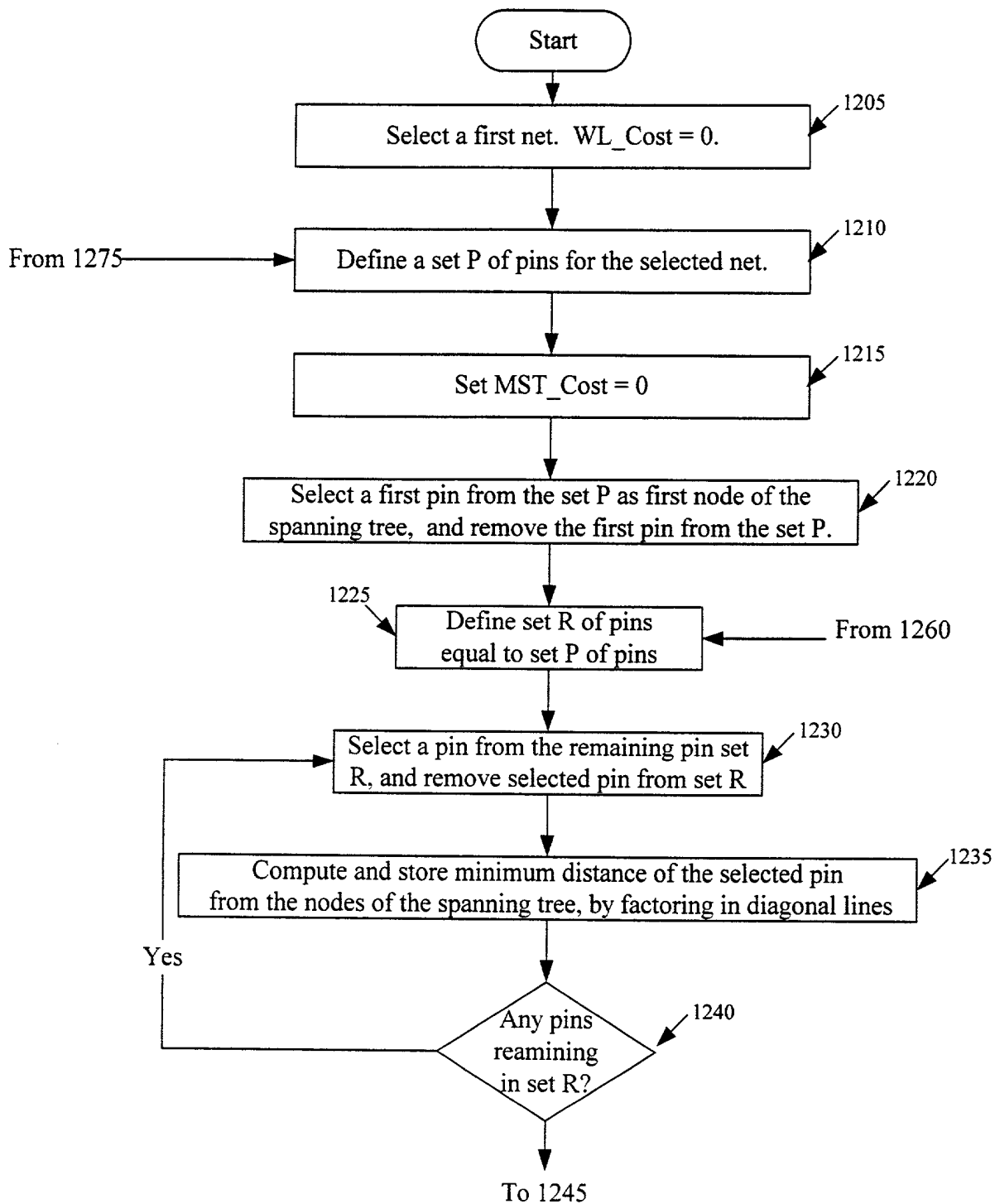


Figure 12A

Figure 12: Figure 12A
Figure 12B

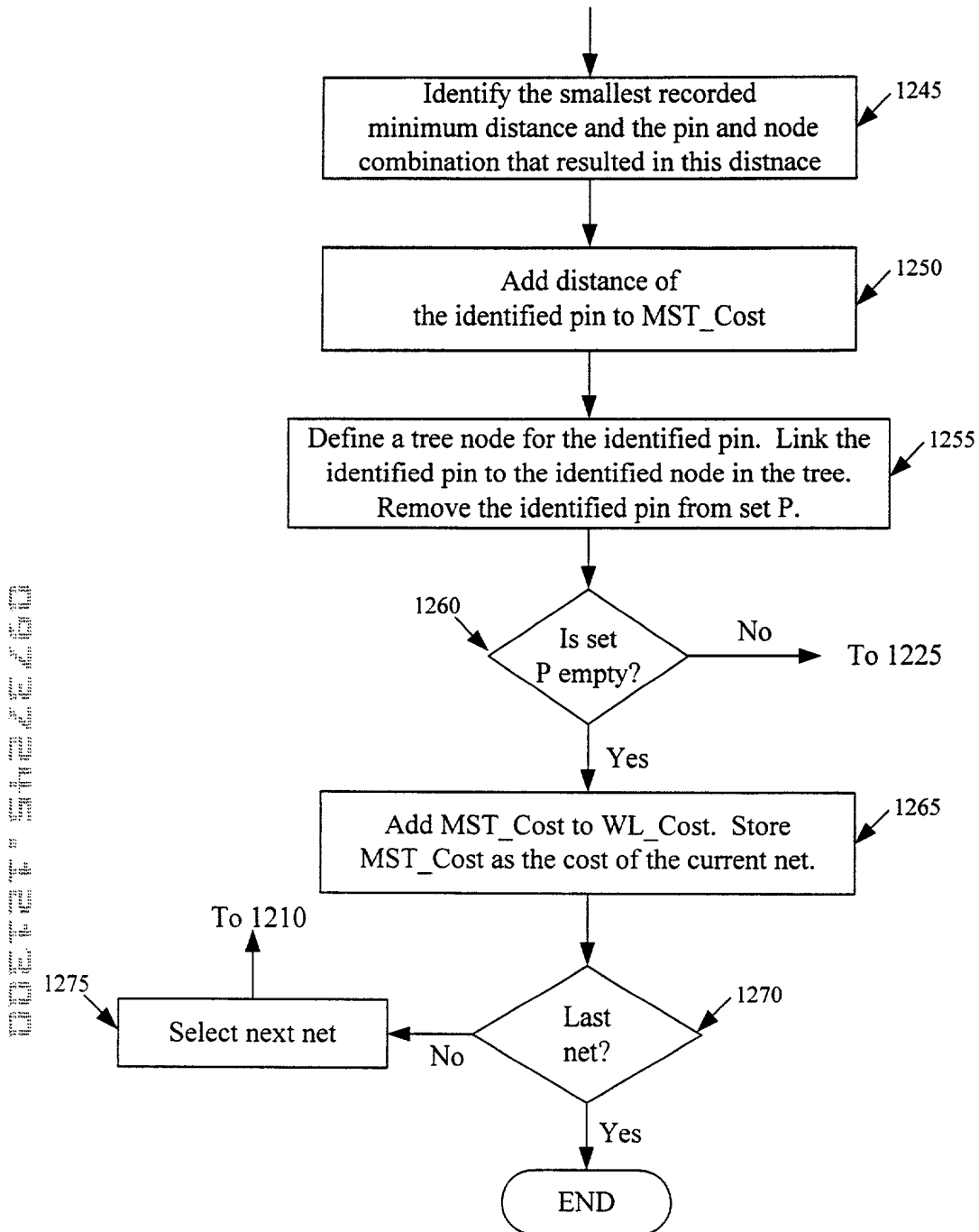


Figure 12B

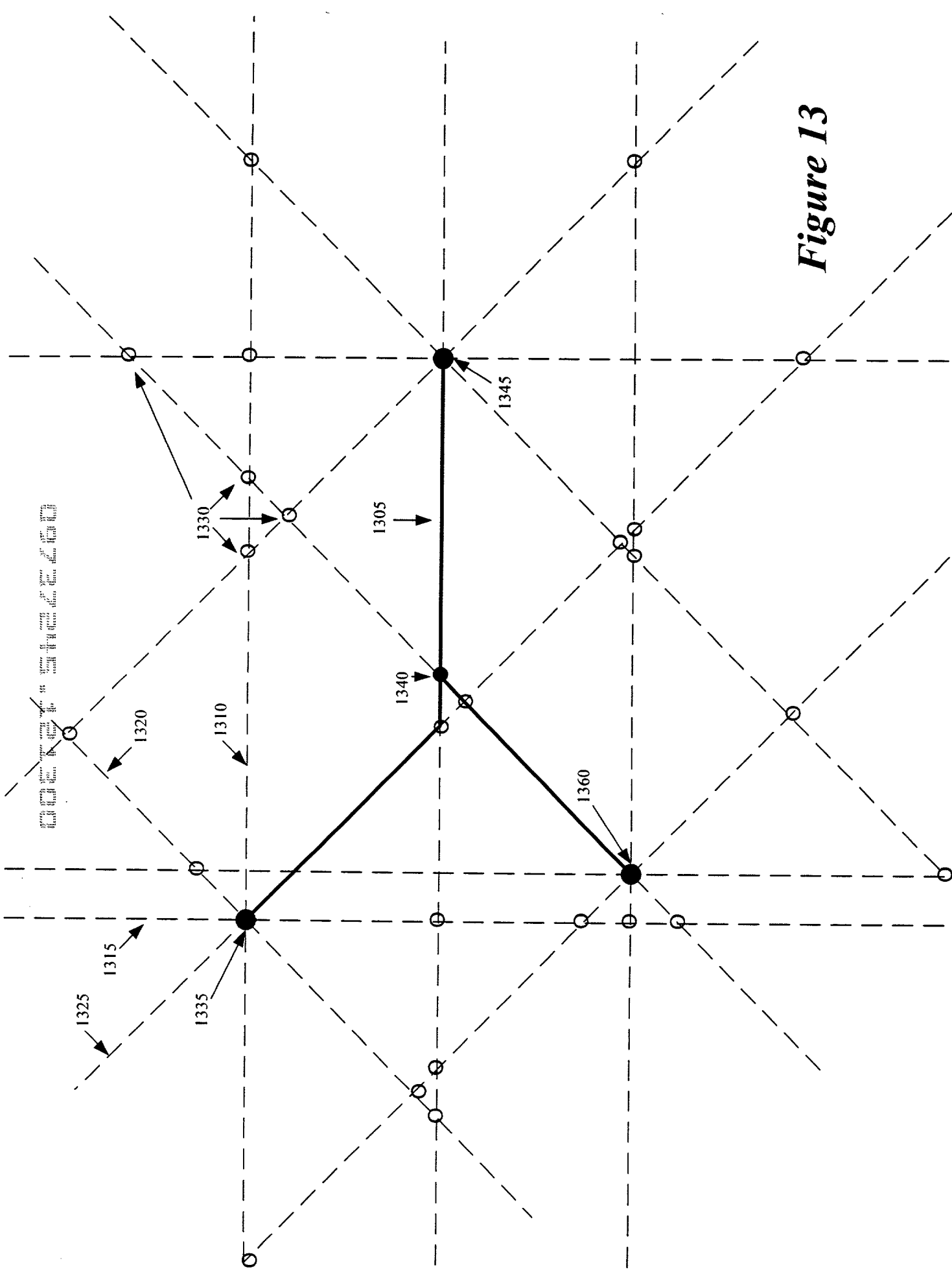


Figure 13

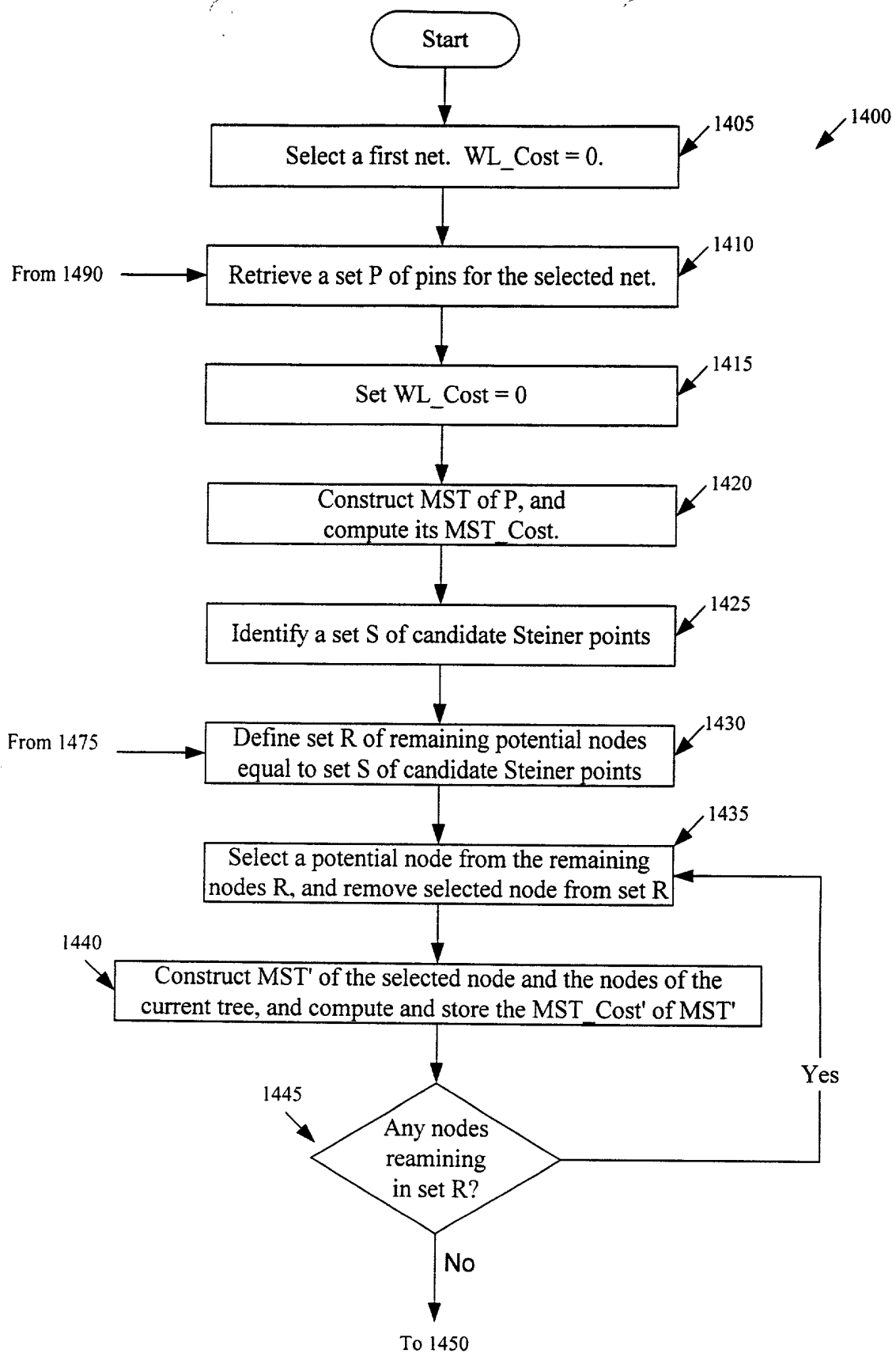


Figure 14: *Figure 14A*
Figure 14A

Figure 14A

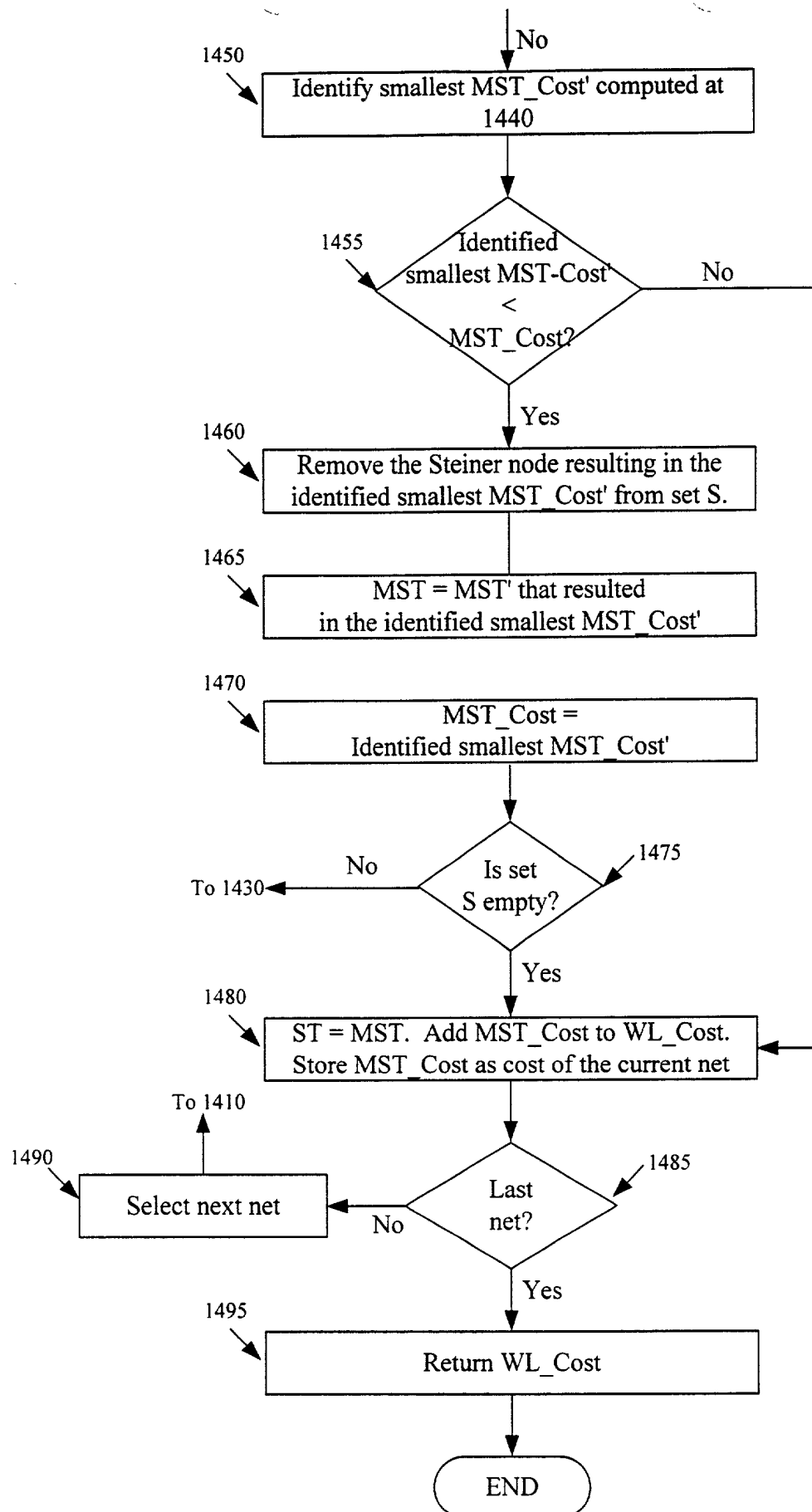


Figure 14B

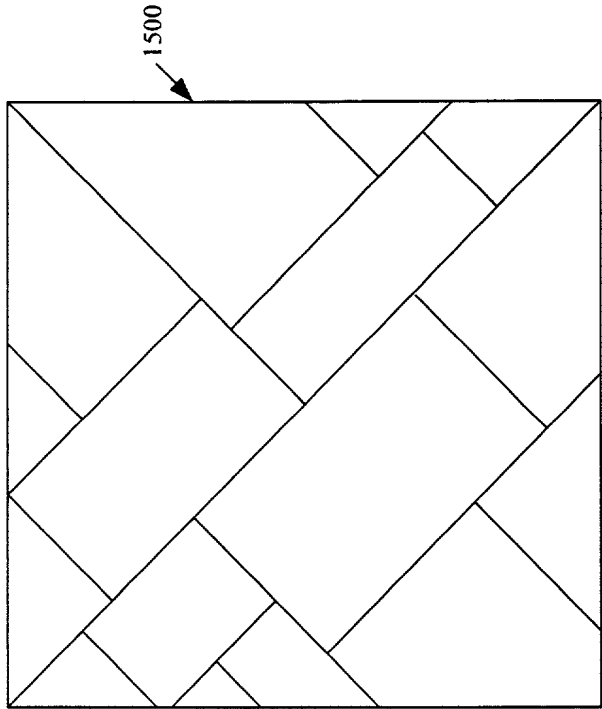


Figure 15

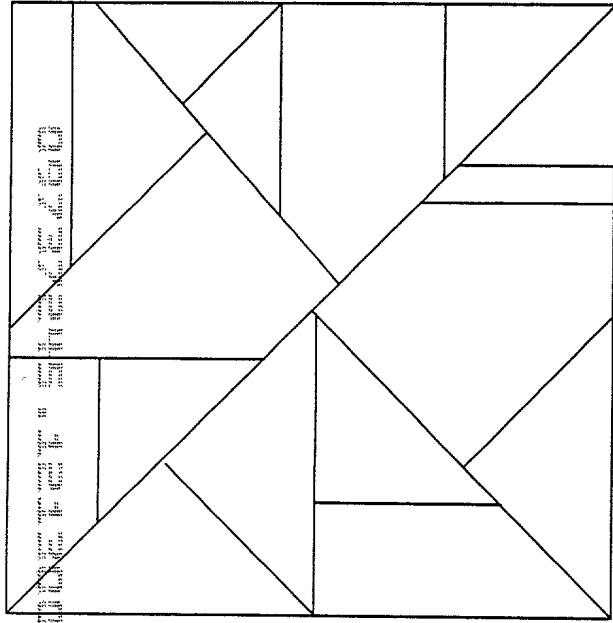


Figure 16

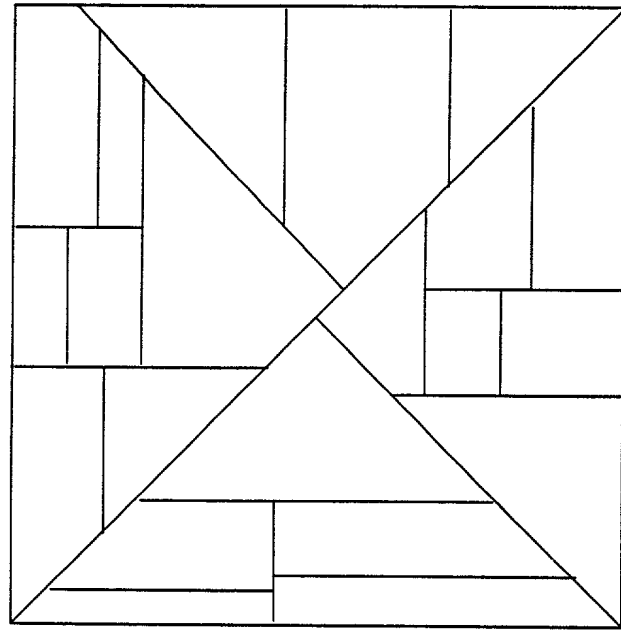


Figure 17

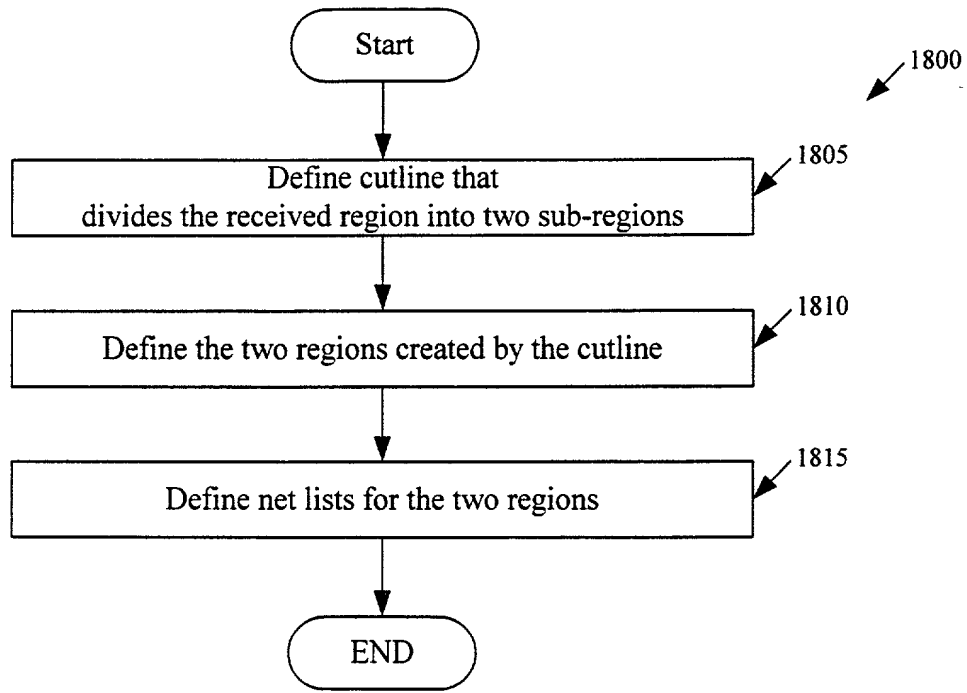


Figure 18

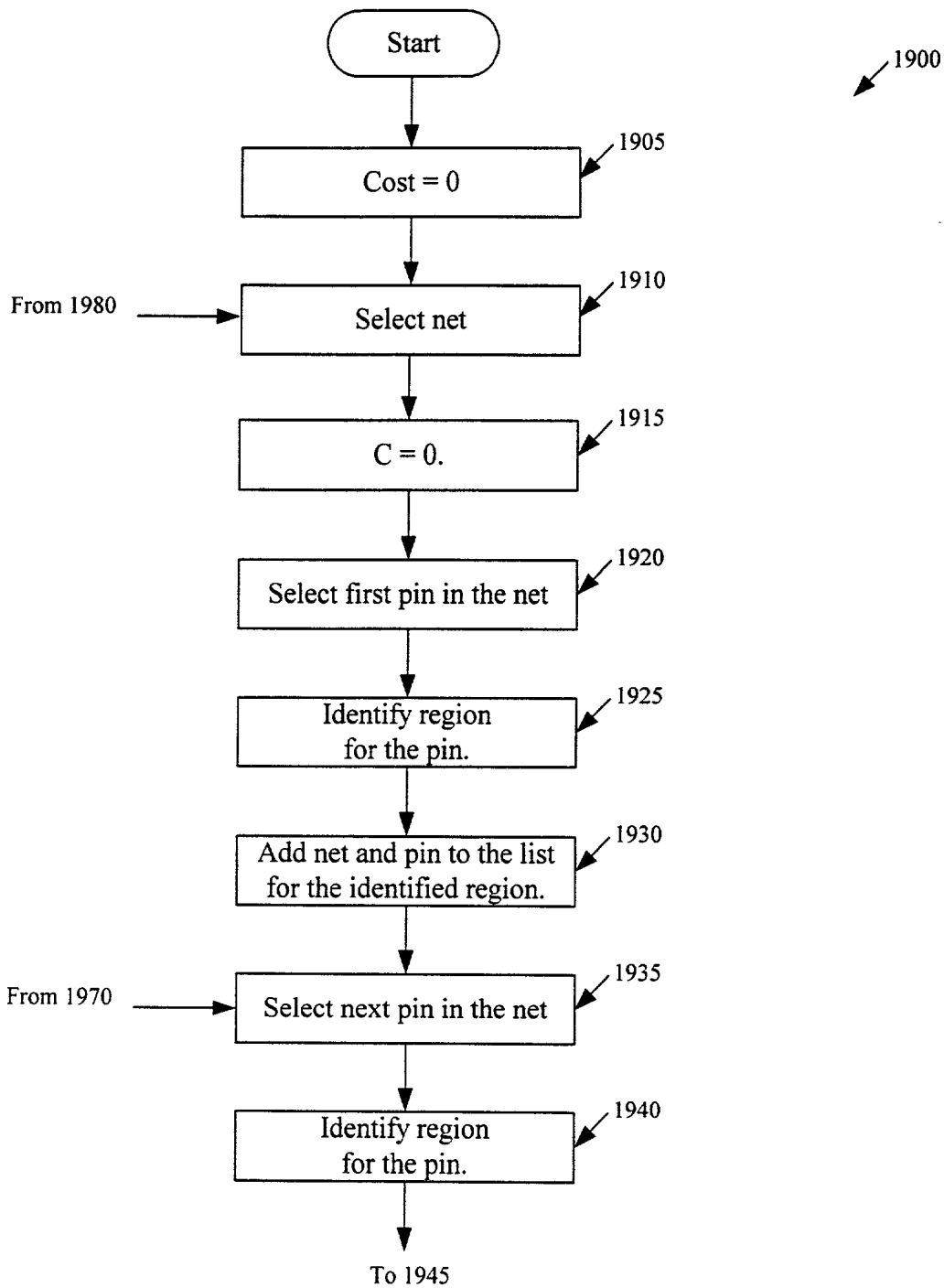


Figure 19A

Figure 19: Figure 19A
Figure 19B

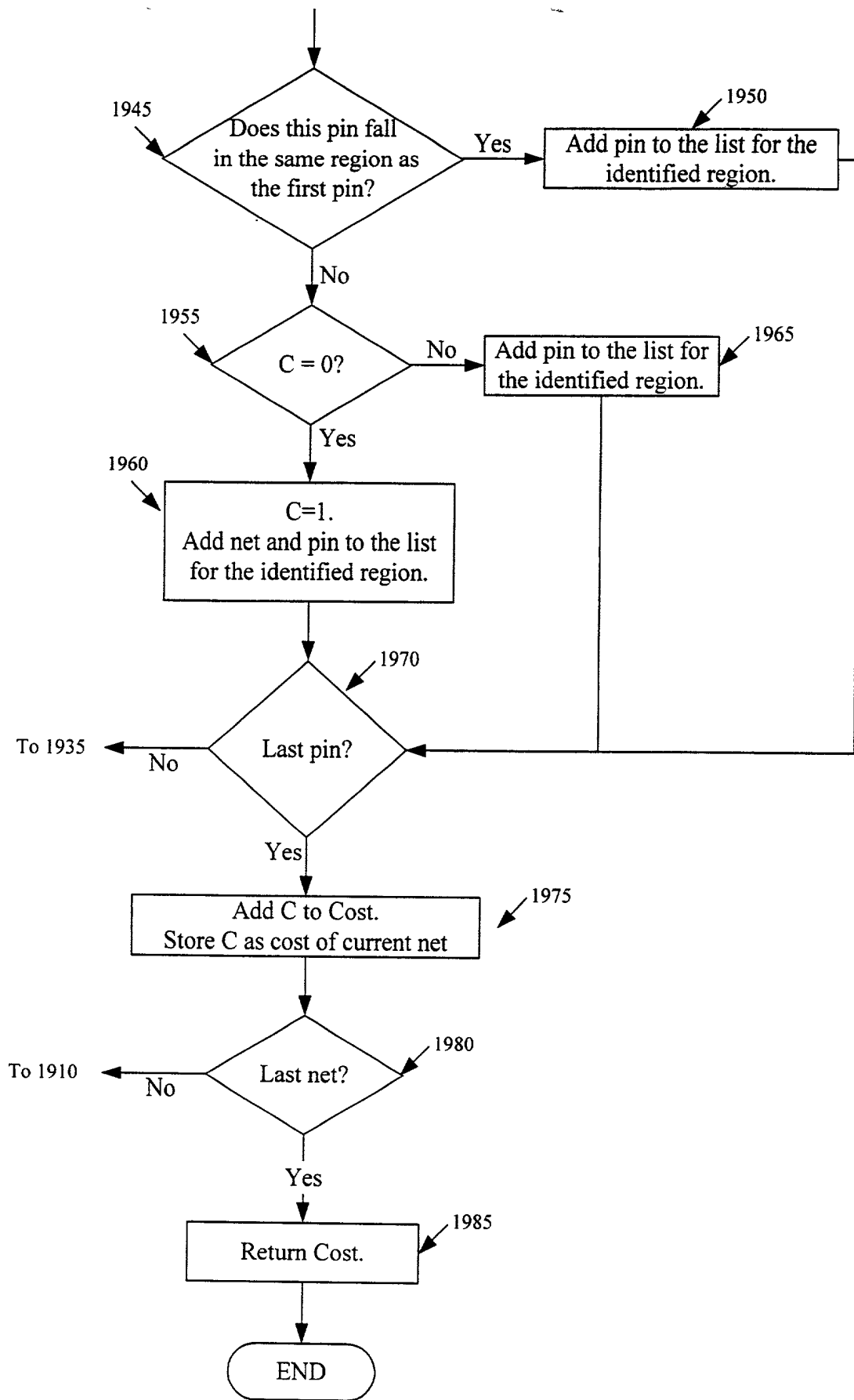


Figure 19B

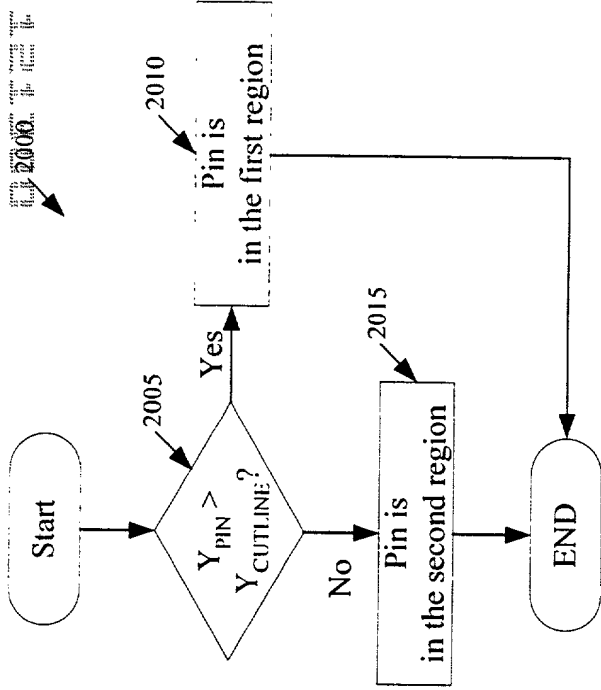


Figure 20

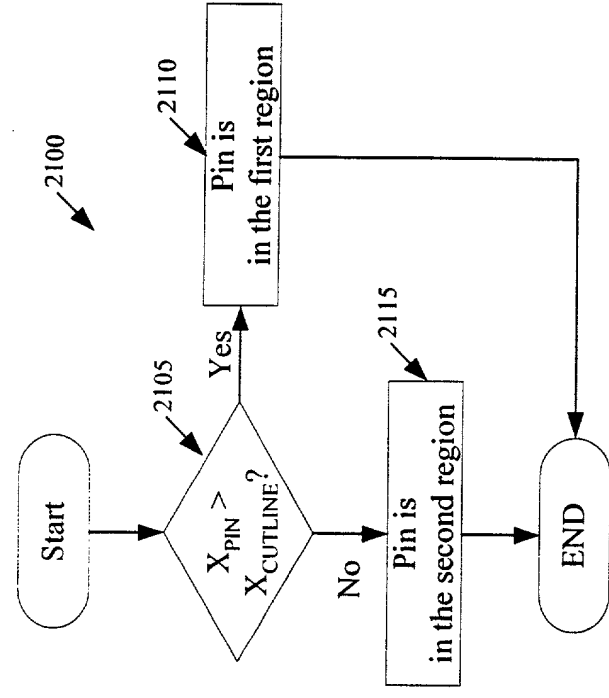


Figure 21

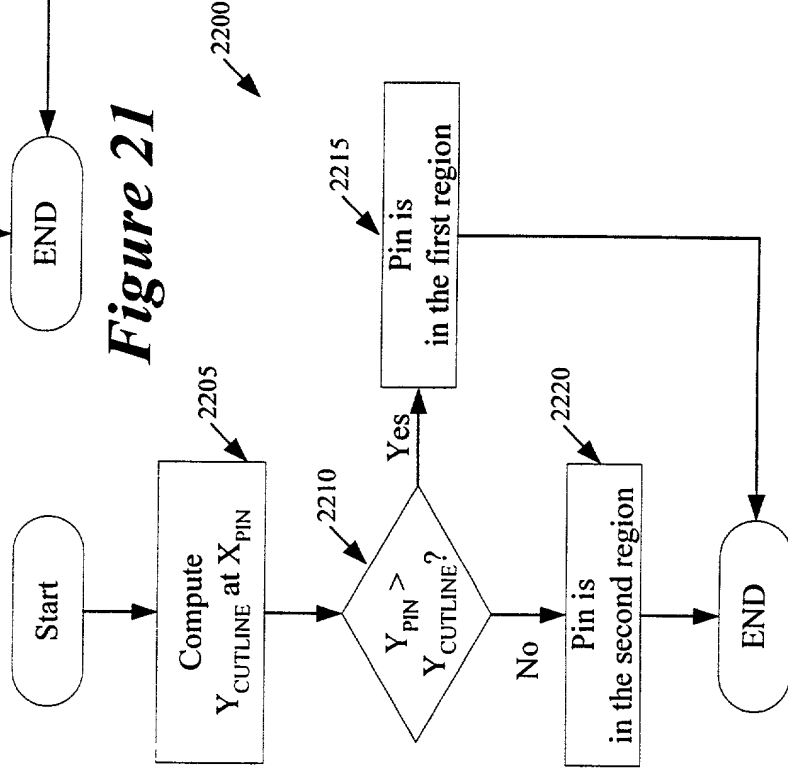


Figure 22

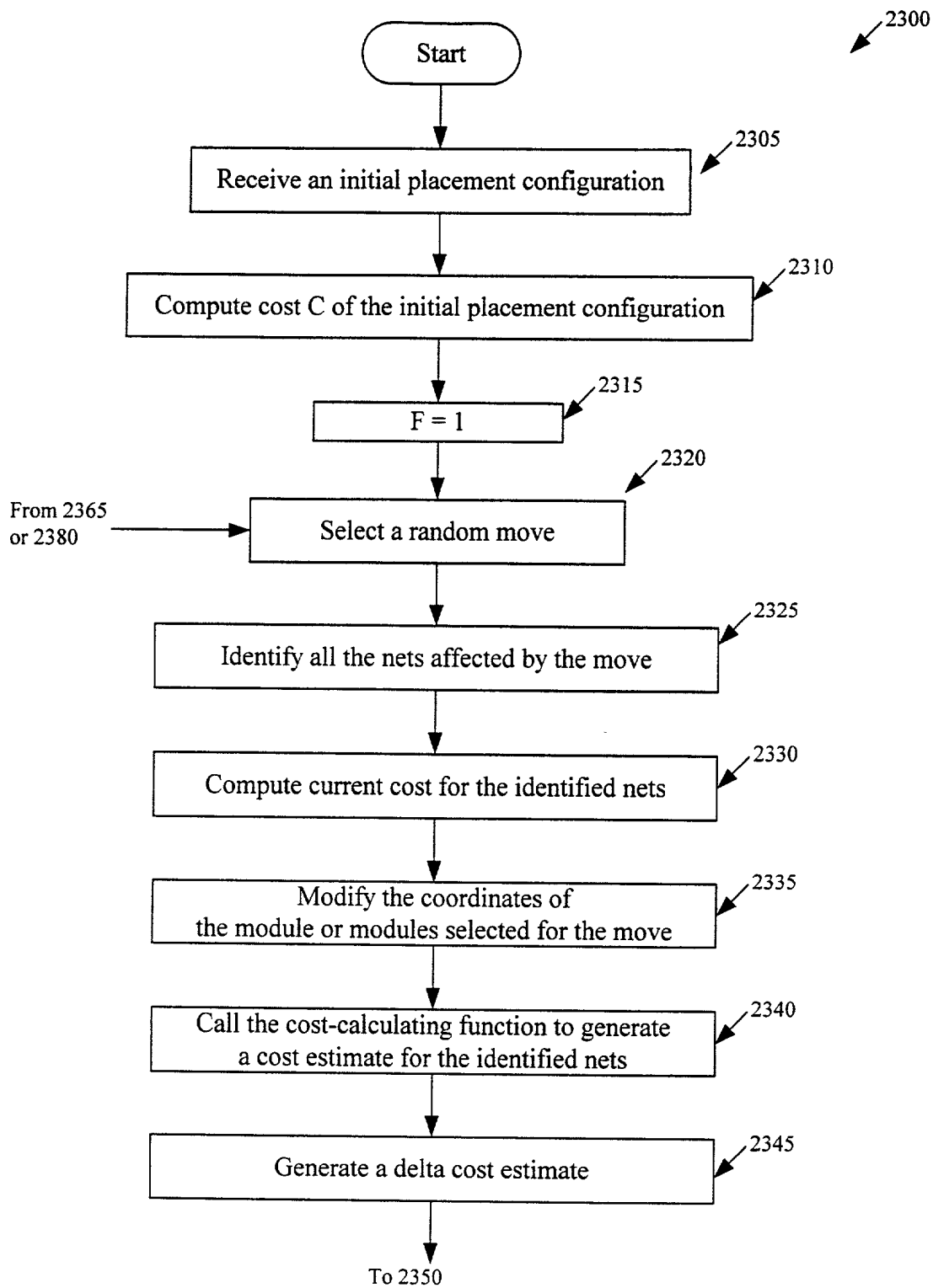


Figure 23A

Figure 23: Figure 23A
Figure 23B

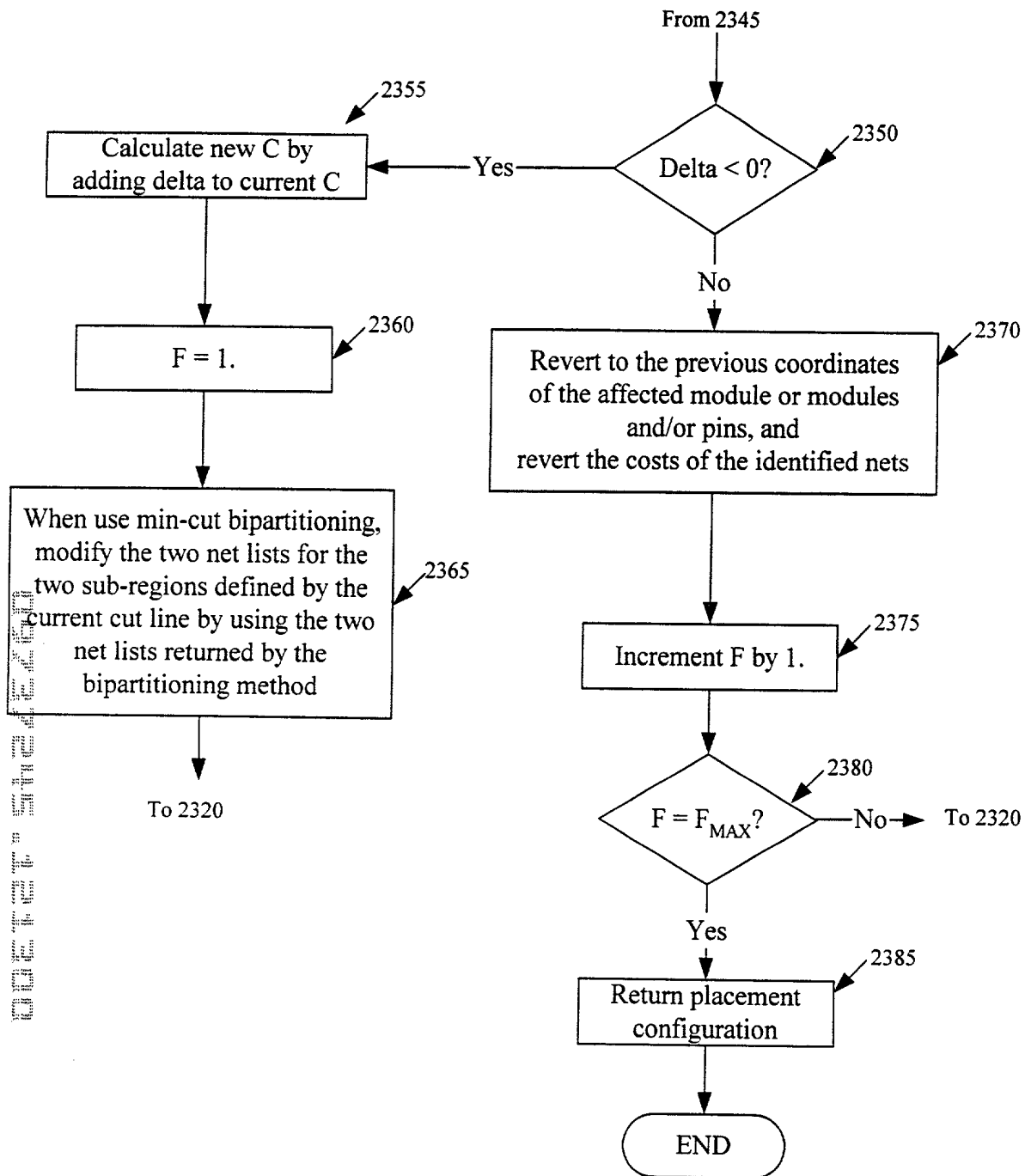


Figure 23B

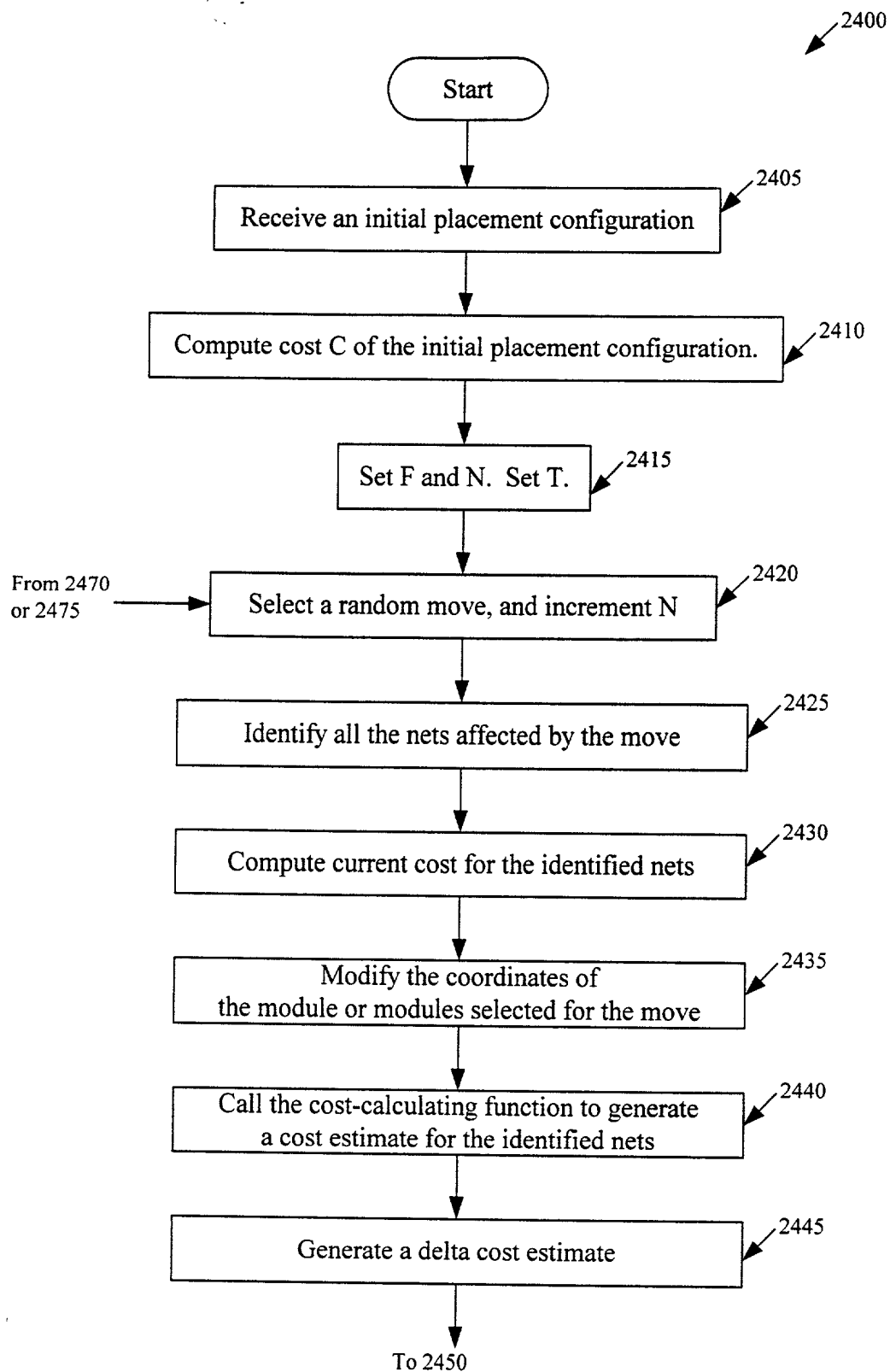


Figure 24A

Figure 24: *Figure 24A*
Figure 24B

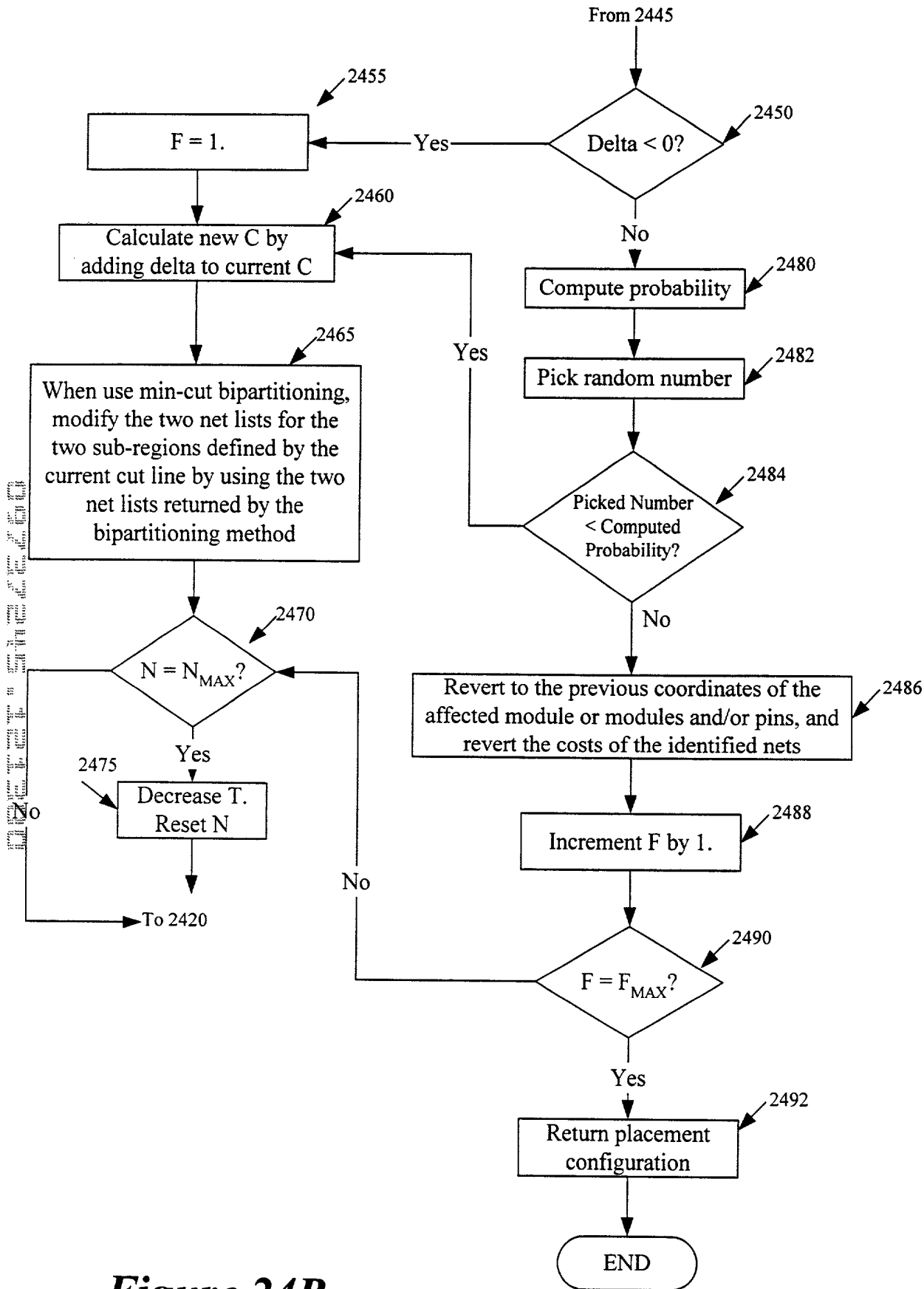


Figure 24B

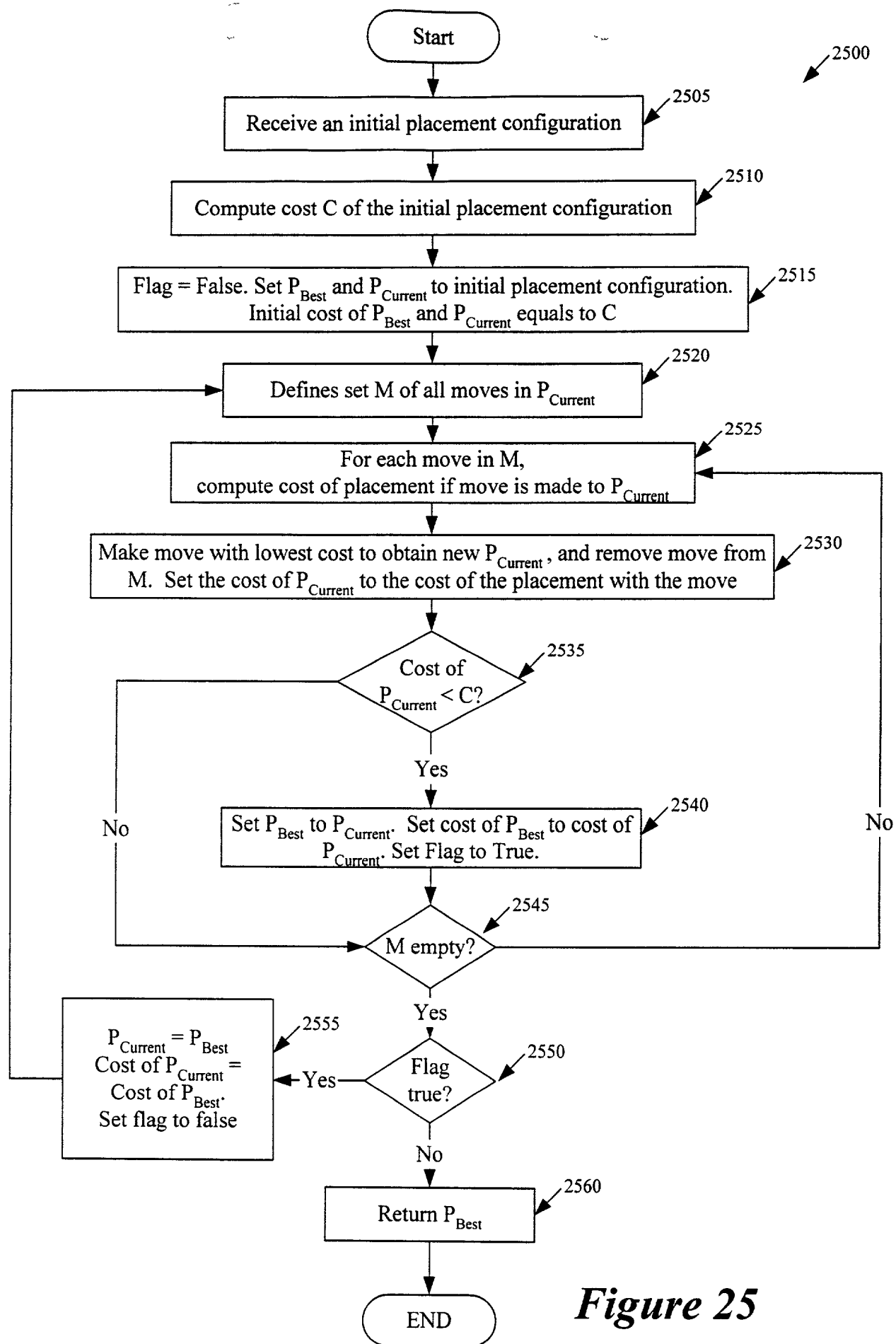


Figure 25

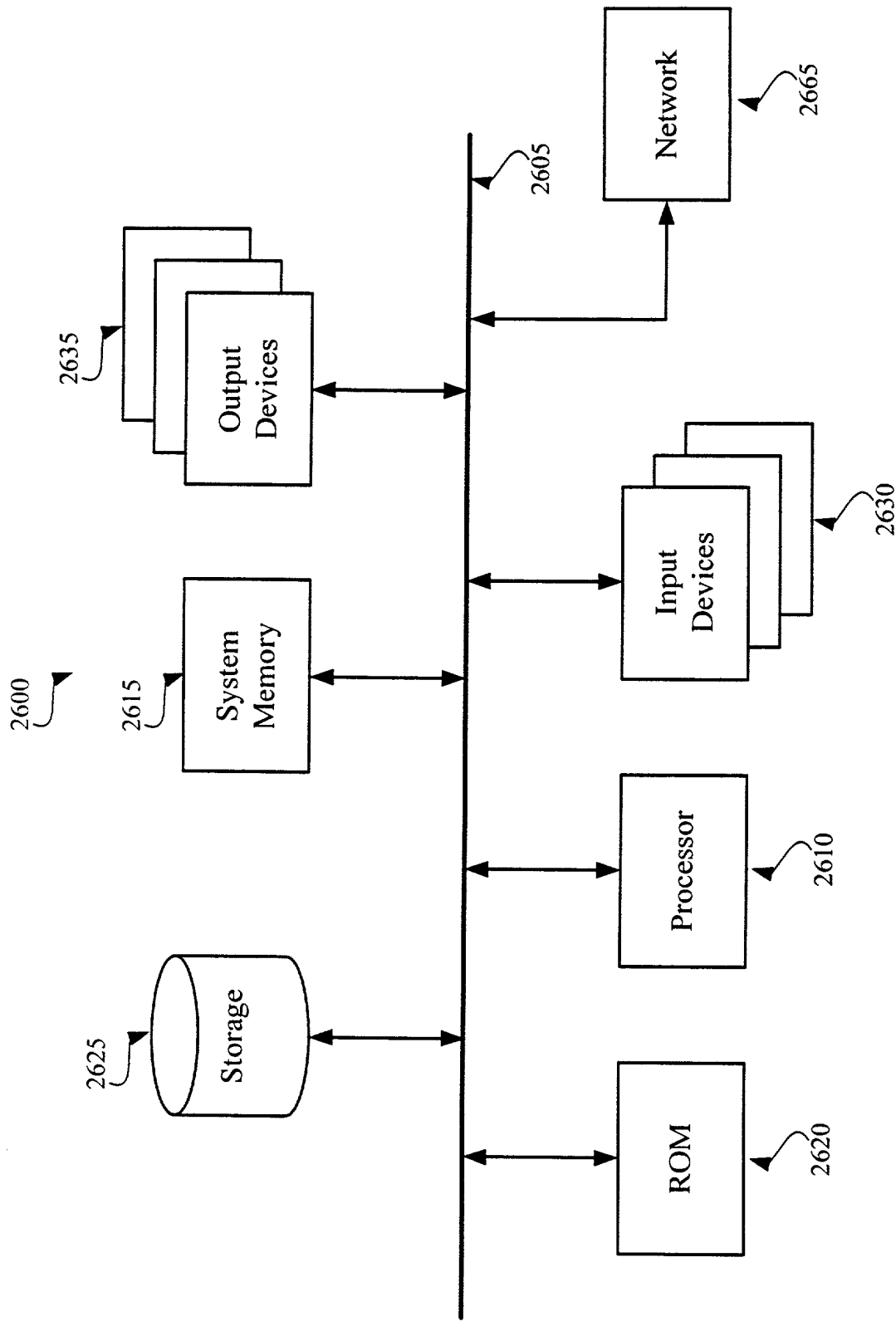


Figure 26